

Detectors: Things you should know

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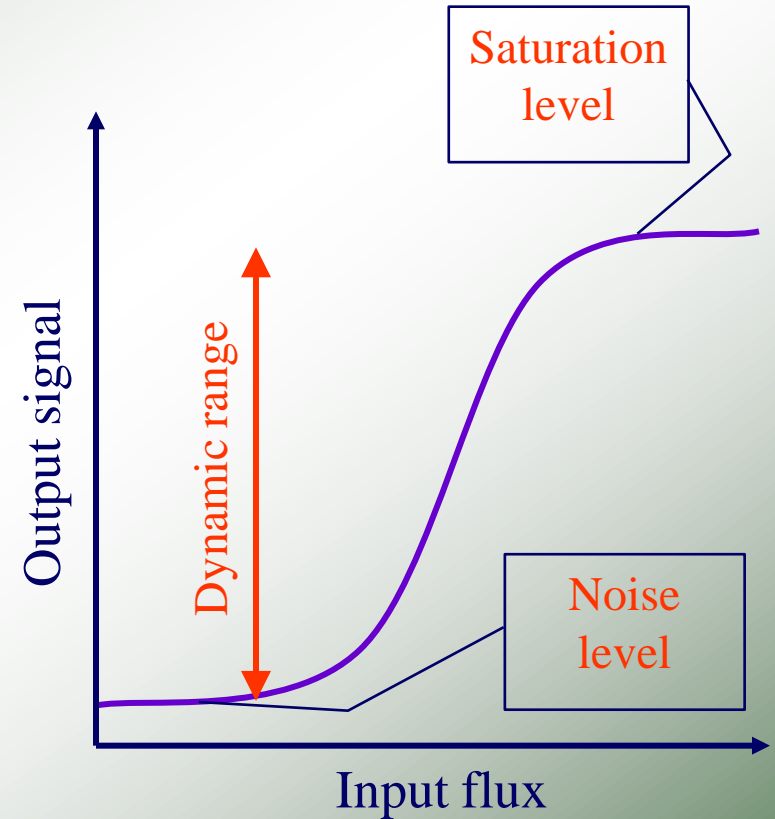
Integrating Detectors

■ Mode

- ◆ Measures deposited energy at end of integration period

■ Characteristics

- ◆ High input flux capability
- ◆ Read noise dominates at low signal (“fog level”)
- ◆ Dead time between frames
- ◆ $2 \times 20 \text{ keV phts} = 1 \times 40 \text{ keV photon}$
i.e. Cannot perform simultaneous spectroscopy and positioning
- ◆ Examples: Image plates, CCDs



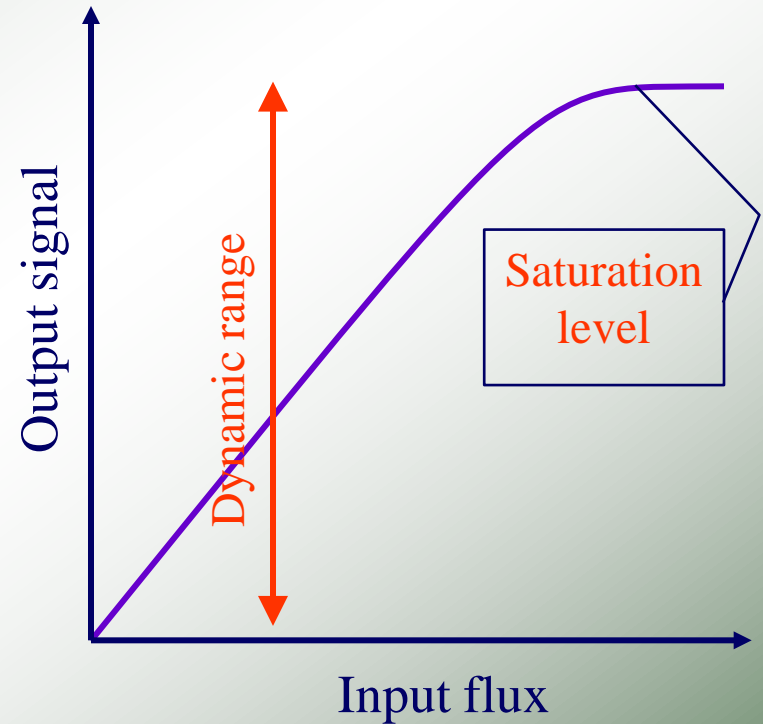
Counting Detectors

■ Mode

- ◆ Detects every particle as it arrives. Only active pixels read

■ Characteristics

- ◆ Quantum limited, Detector noise often negligible
- ◆ No dead time between frames
- ◆ Can measure position and energy simultaneously
- ◆ Limited input flux capability
- ◆ Examples: Geiger counters, Pilatus, Scintillators

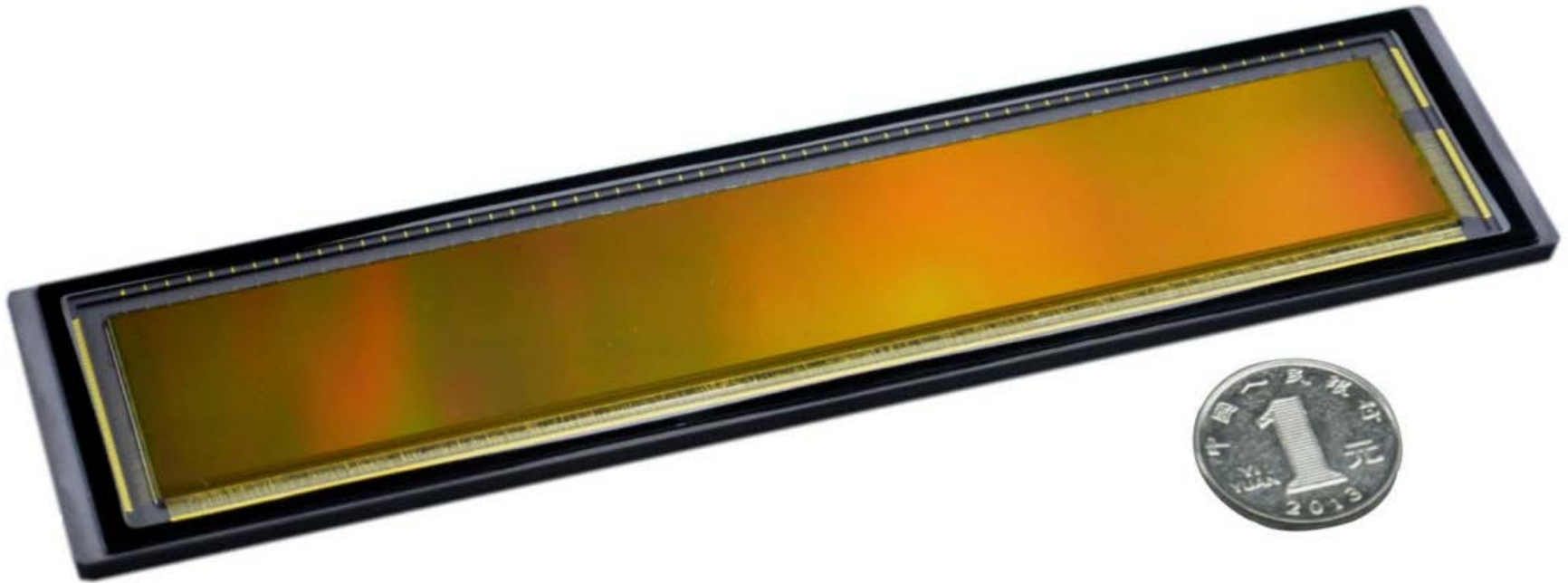


Big CMOS



GMAX3005

150 Megapixels Full-Frame CMOS Image Sensor - GMAX3005



Specifications



GMAX3005

SENSOR SPECIFICATIONS

Photon-sensitive area	165mm(H) x 27.5mm(V)	SNR Max	43dB
Pixel size	5.5 μ m \times 5.5 μ m	Dark noise	3.94e-
Resolution	150MP - 30,000 \times 5,000	Dark current	<10e-/s/pix (32 $^{\circ}$ C)
Shutter type	electronic rolling shutter	Dynamic range	67dB (Intra-scene)
ADC	16bit	Dynamic range	75.4dB
Main clock rate	20MHz ~30MHz	Sensitivity (PGA=5.6x)	255DN/nJ/cm ²
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Data rate	24Gbit/s @10fps	Output interface	120 LVDS pairs
Supply voltage	3.3V / 1.8V	Operating temperature	-55 $^{\circ}$ C ~ +85 $^{\circ}$ C
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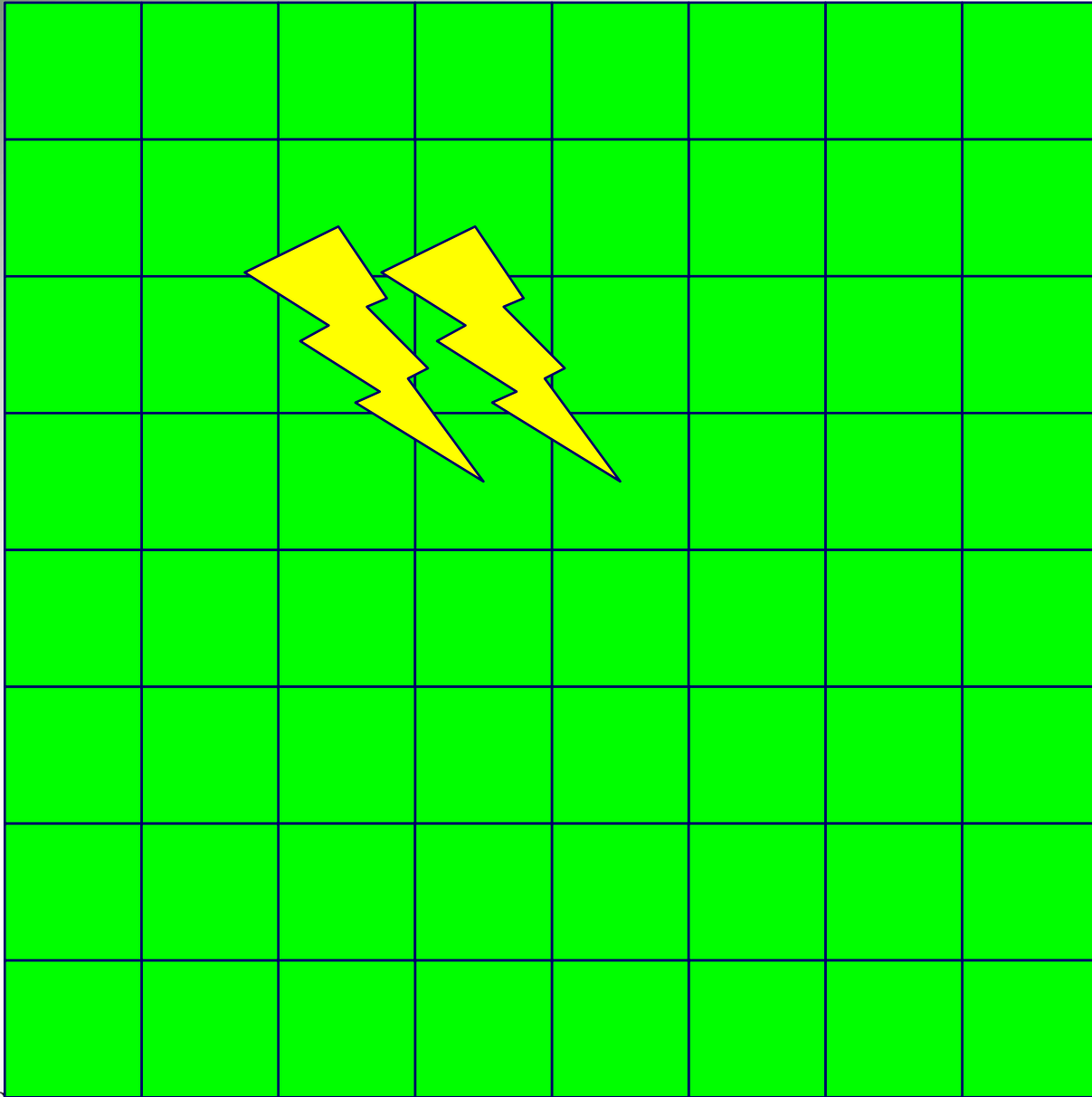


GMAX3005

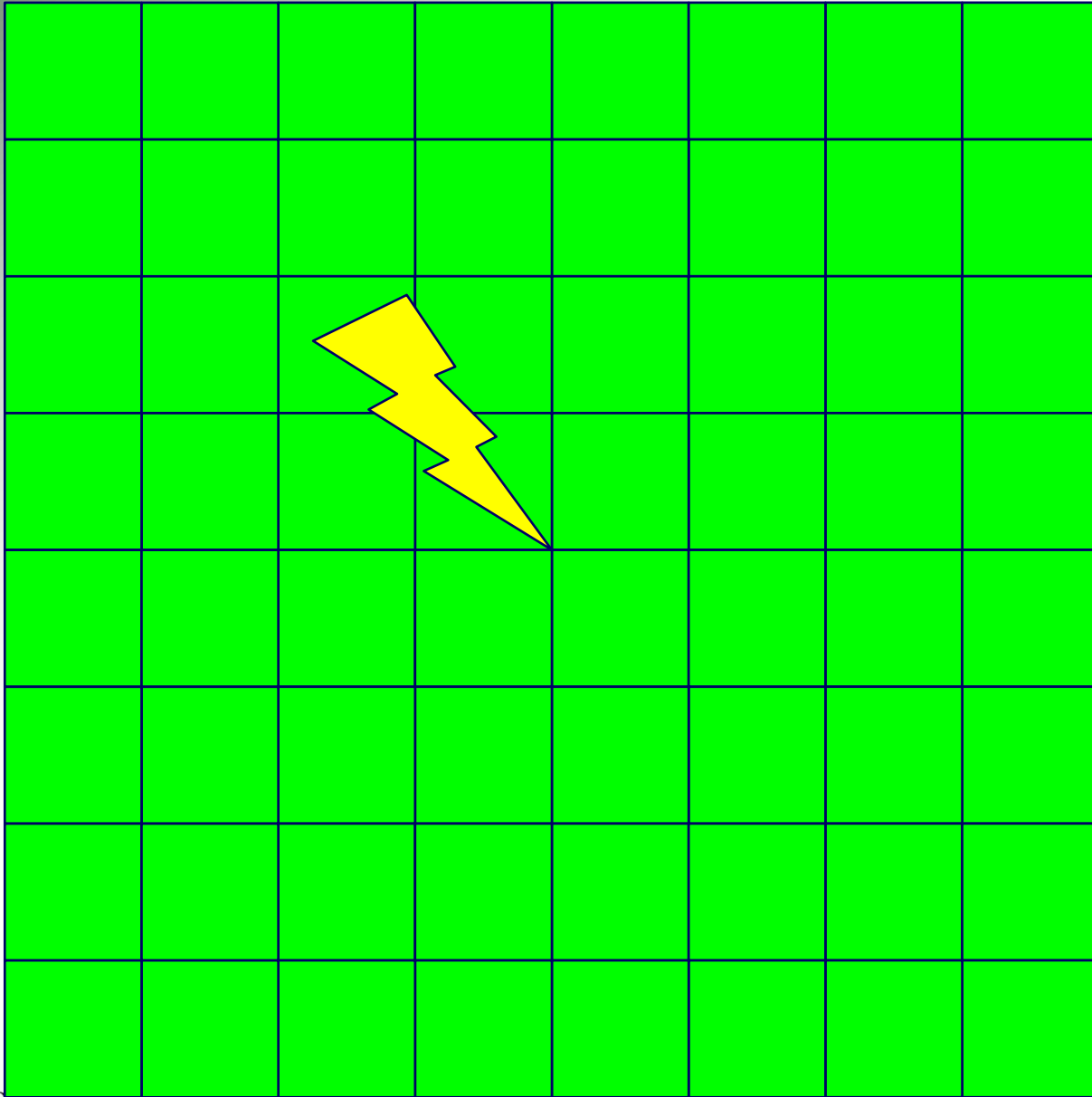
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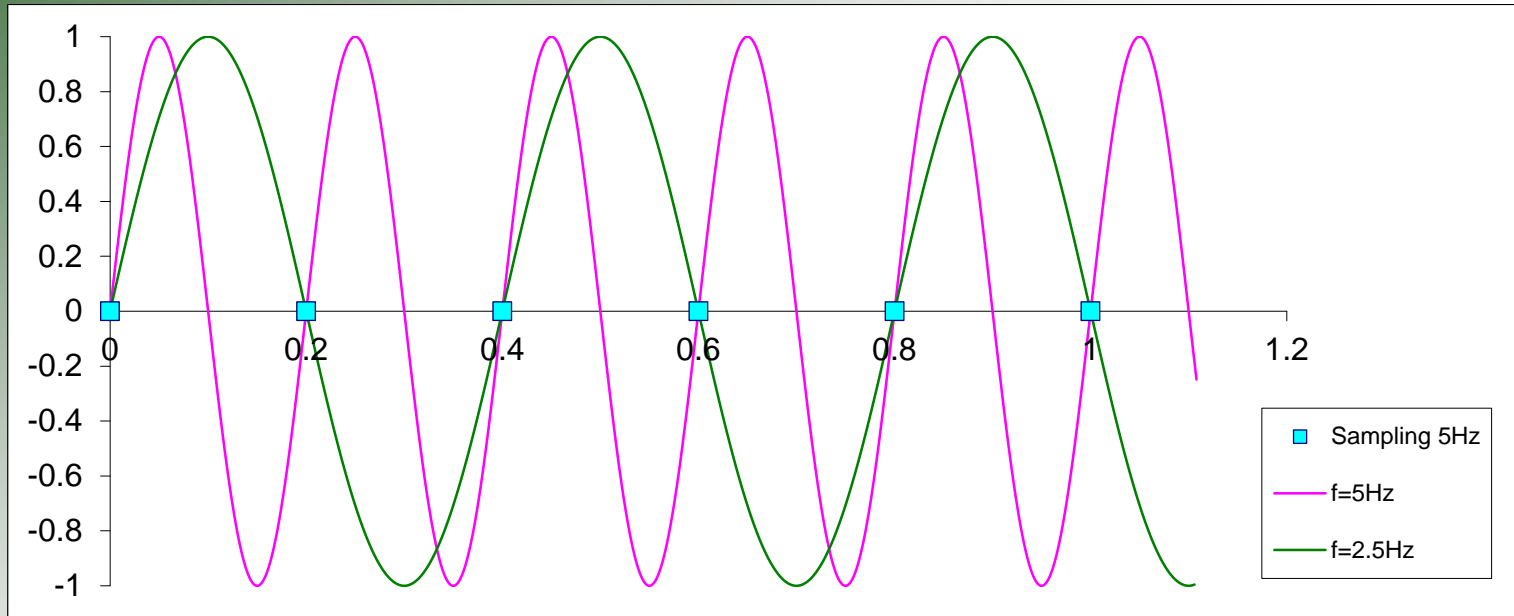
Resolution is NOT pixel size



Resolution is NOT pixel size



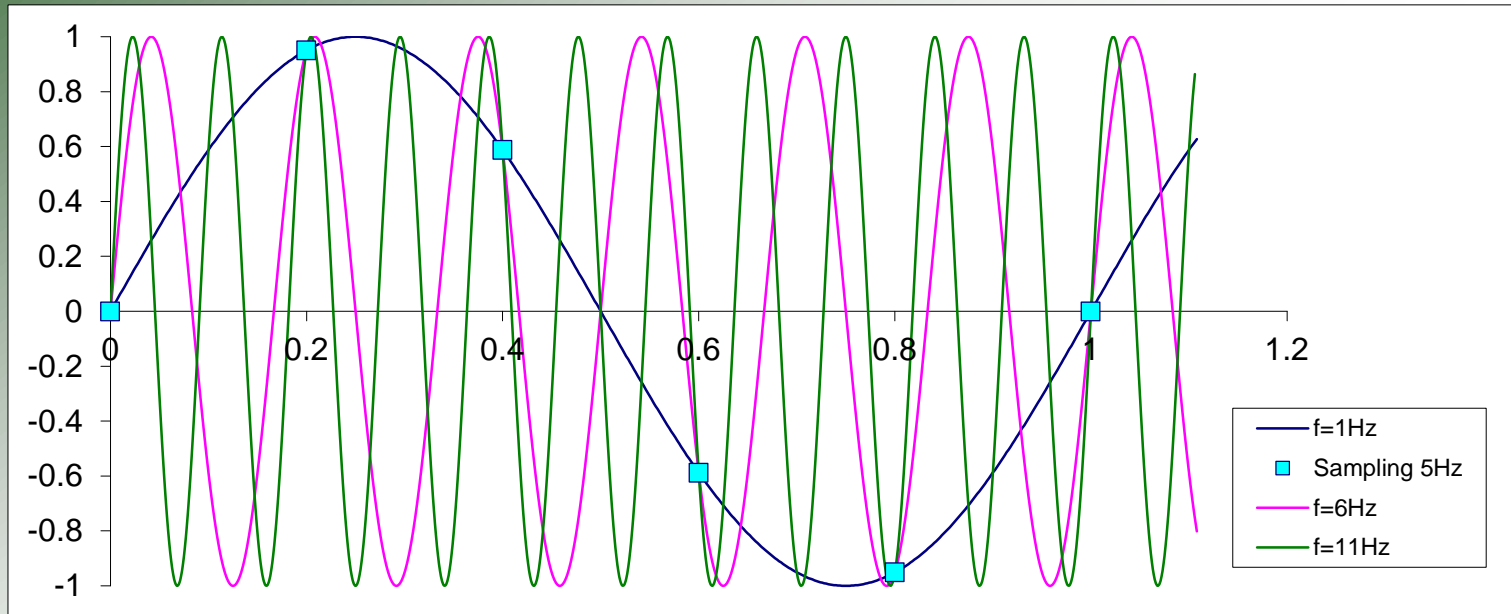
Sampling



■ Shannon's Theorem and Nyquist Criterion

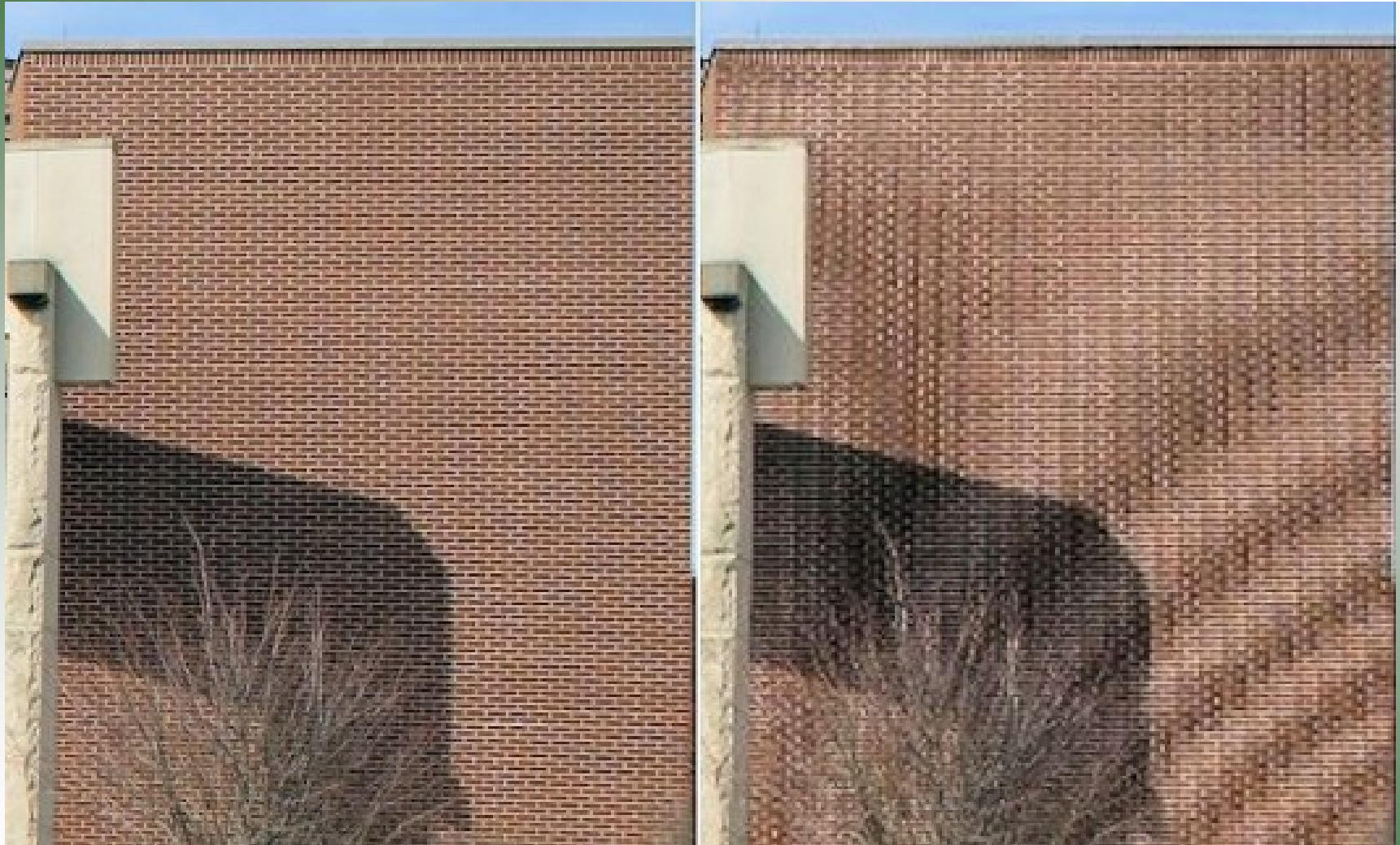
- ◆ The highest frequency that can be 'measured' is HALF the sampling frequency

Aliasing



- If the input is not band limited to frequencies less than $f_s/2$, then aliasing will occur at frequencies $f \pm nf_s$
 - ◆ where f = signal frequency, f_s = sampling frequency, n = integer
- If you have $100\mu\text{m}$ pixels, the very best spatial resolution that you can expect (in the absence of noise) is $200\mu\text{m}$
- In any real system $> 200\mu\text{m}$
- And that is all assuming NO DISTORTIONS!!

Aliasing



Specifications



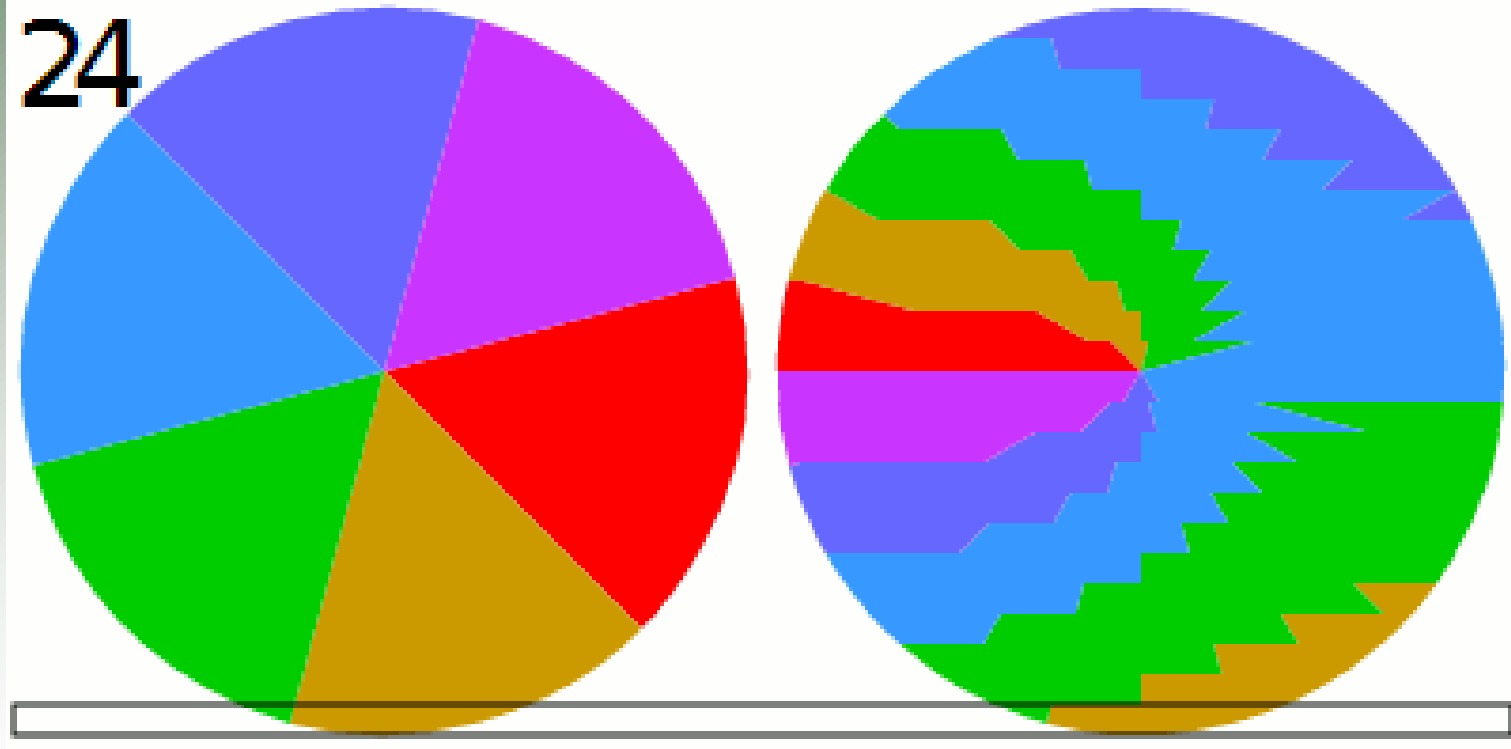
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Electronic Rolling Shutter

24



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Data Rates

- 120 LVDS pairs at 200Mbps = 24Gbps

- ◆ LVDS = Low Voltage Differential Signalling

- Interfaces

- ◆ USB2: 480 Mbps
- ◆ USB3: 5 Gbps
- ◆ USB3.1: up to 10 Gbps???
- ◆ SATA III: 6 Gbps
- ◆ Thunderbolt 2: 10 Gbps

- Disk write speeds

- ◆ HDD: 200 Mbps
- ◆ SSD: 530 Mbps

- So 45 SSDs in parallel required to store data!!!!

Specifications



GMAX3005

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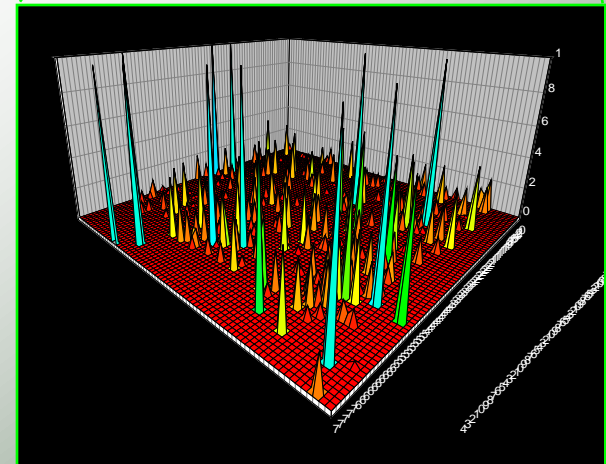
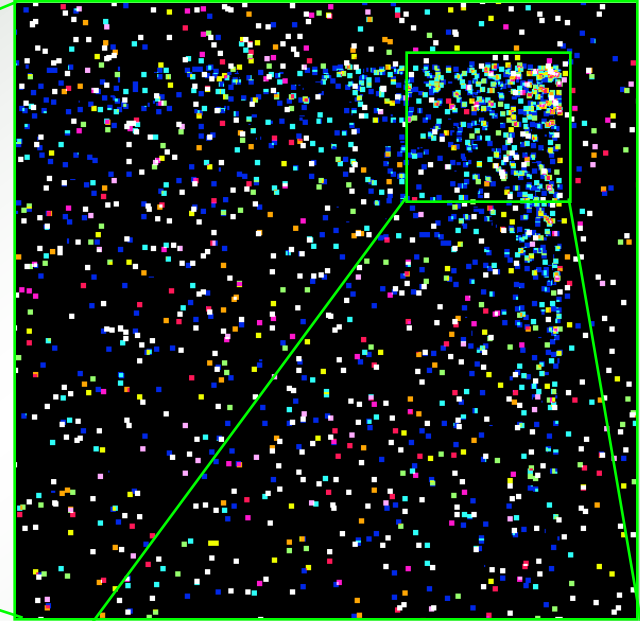
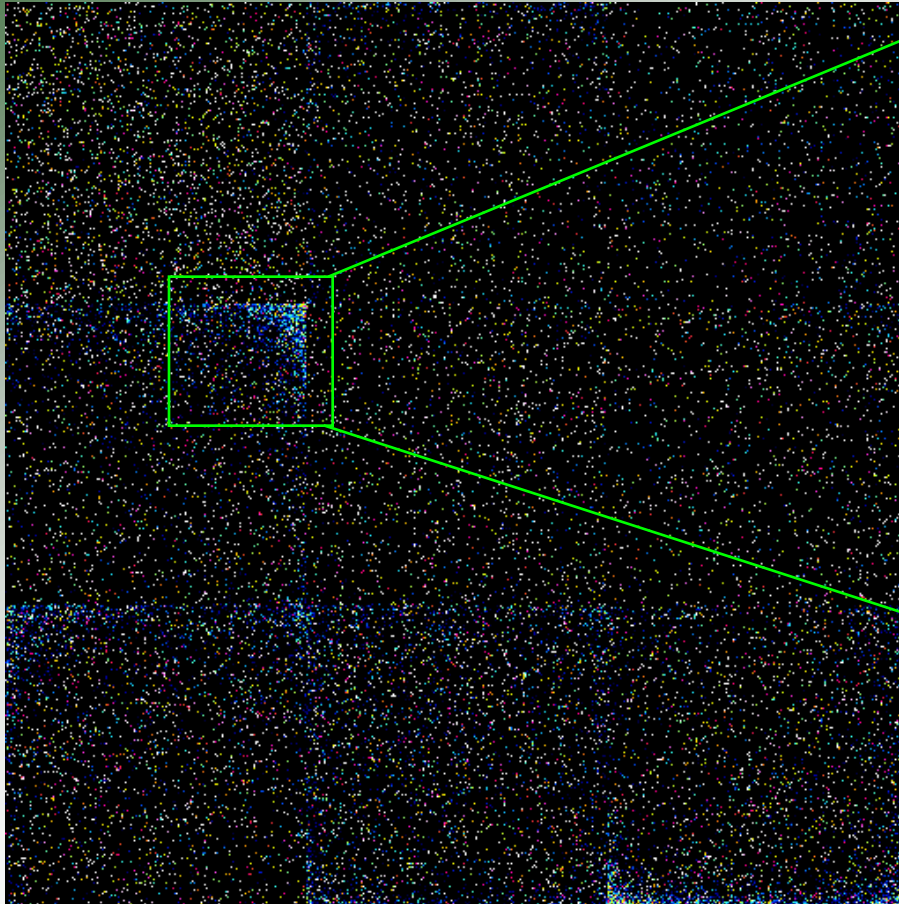
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Dark Current

- Dark current is the signal produced under zero illumination
- Dark noise is a measure of the fluctuations in dark current
- Dark noise sets the minimum detectable signal

Dark Current

Pixels above the 0.2 photons pix^{-1} specification



Number failing 2 measurements 5-2000s

Mean	44764	0.47%
Min	40822	0.43%
Max	48706	0.52%

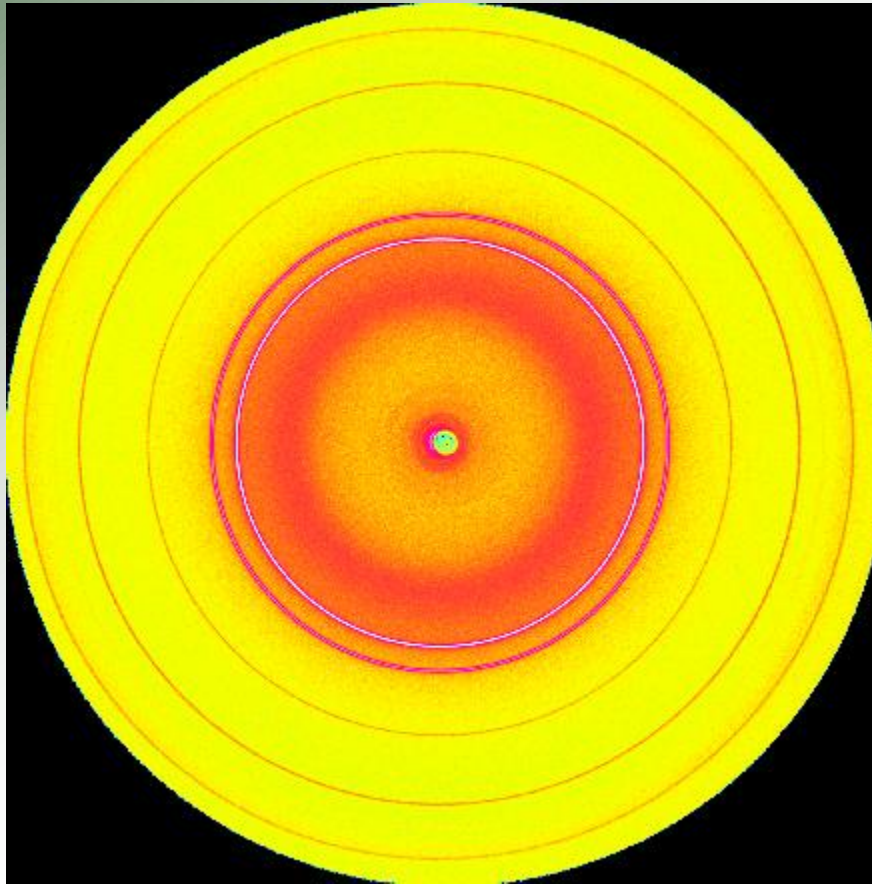
nb. 14300 pixels not common to both

dpiX Flashscan 30 PaxScan 4030



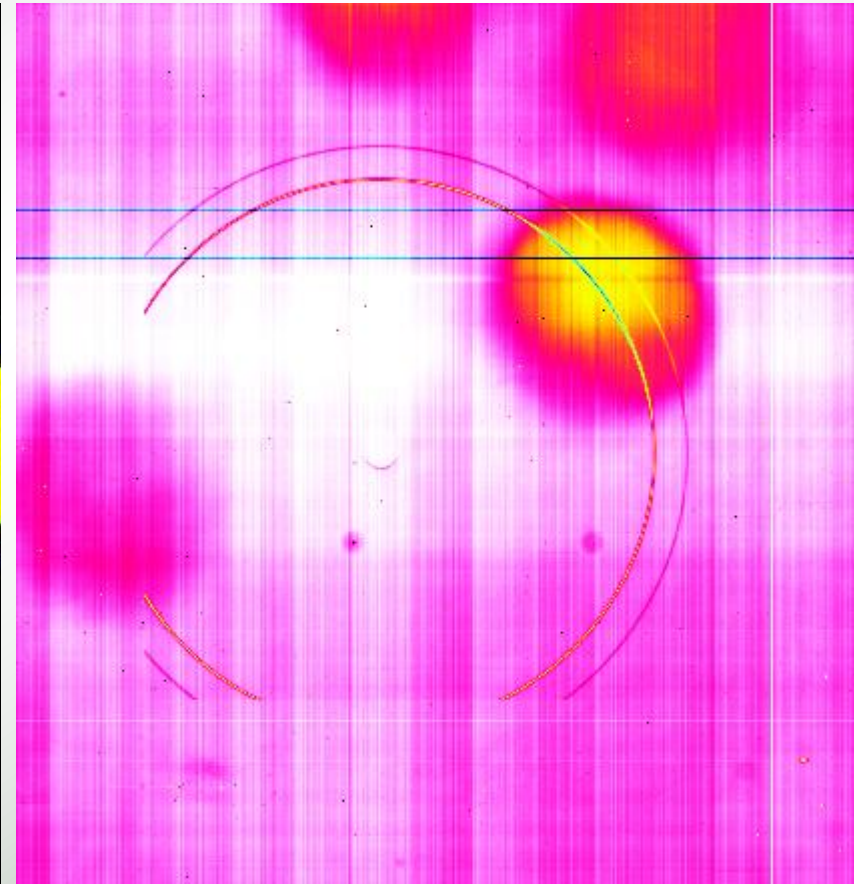
Flashscan 30 - Performance

Mar Image Plate



$t_{\text{int}}=30\text{s}$

Flashscan-30



$t_{\text{int}}=190\text{s}$

Specifications

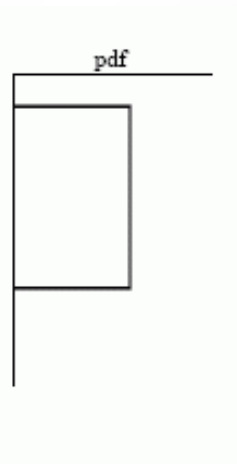
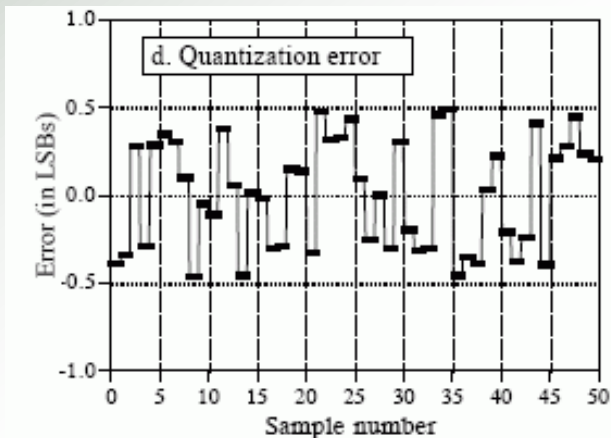
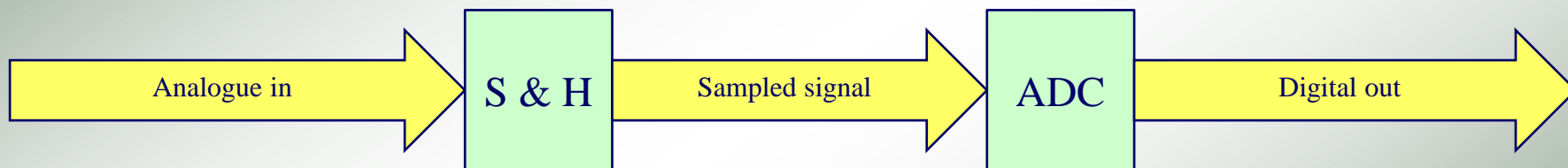
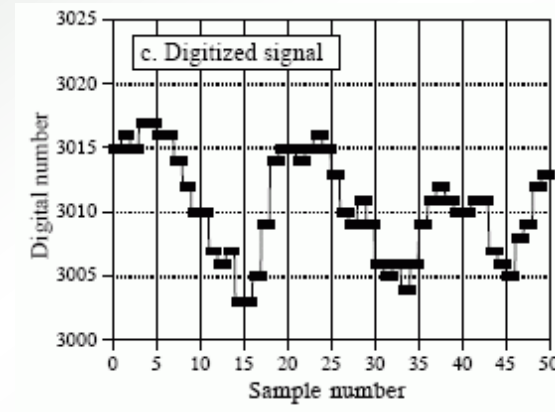
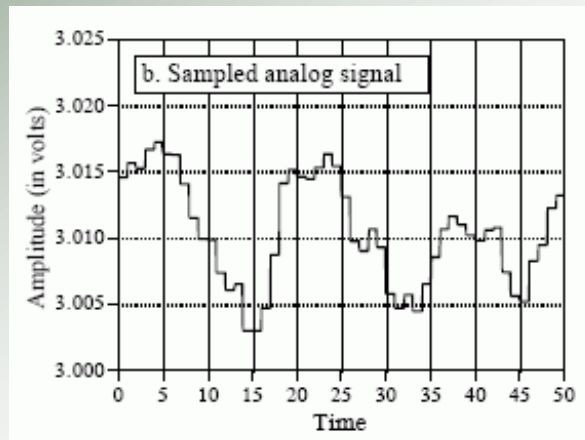
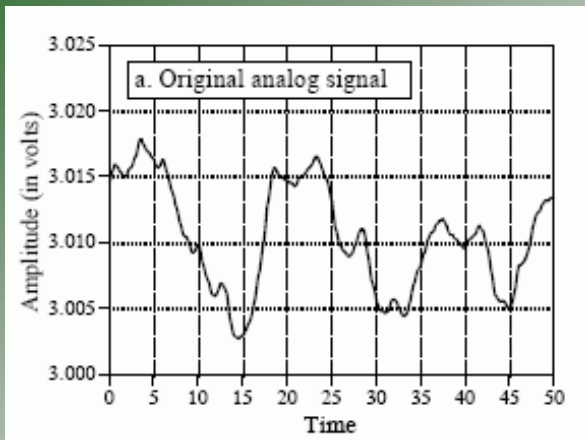


GMAX3005

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Quantisation Error



- Quantisation errors are $\pm 1/2$ LSB
- Quantisation errors look like random noise and can be treated as such

ADC Resolution and Noise

- Max noise is $\pm 1/2$ LSB
- Standard deviation $\sigma = \left(1/\sqrt{12}\right)LSB$ (Uniform pdf)

nBits	8	10	12	16
nLevels	256	1024	4096	65536
Quantisation error (%)	0.113	0.028	0.007	0.0015
Dynamic Range (dB)	48	60	72	96

- More bits usually means slower and more expensive
- Dynamic range is max signal divided by min signal
- Number of bits sets max dynamic range
- Often expressed in dB where $dB = 20 \log_{10}$ (Ratio)

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■ All these are interrelated

Specifications

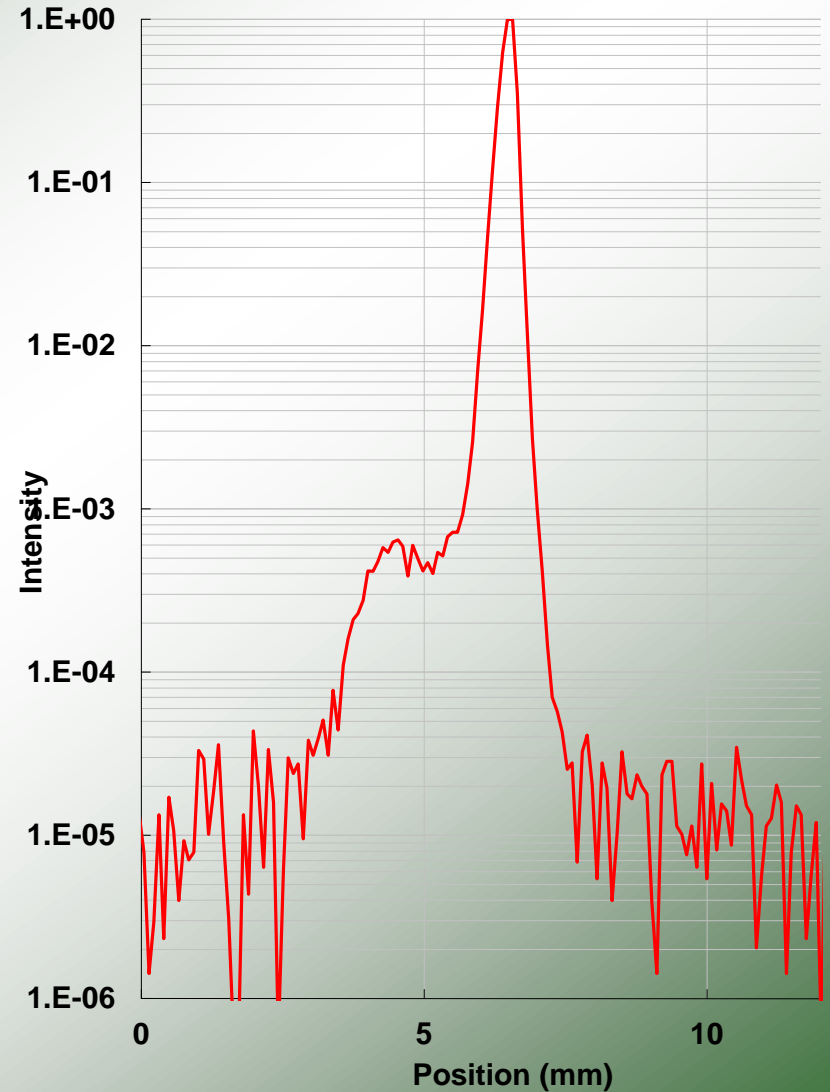
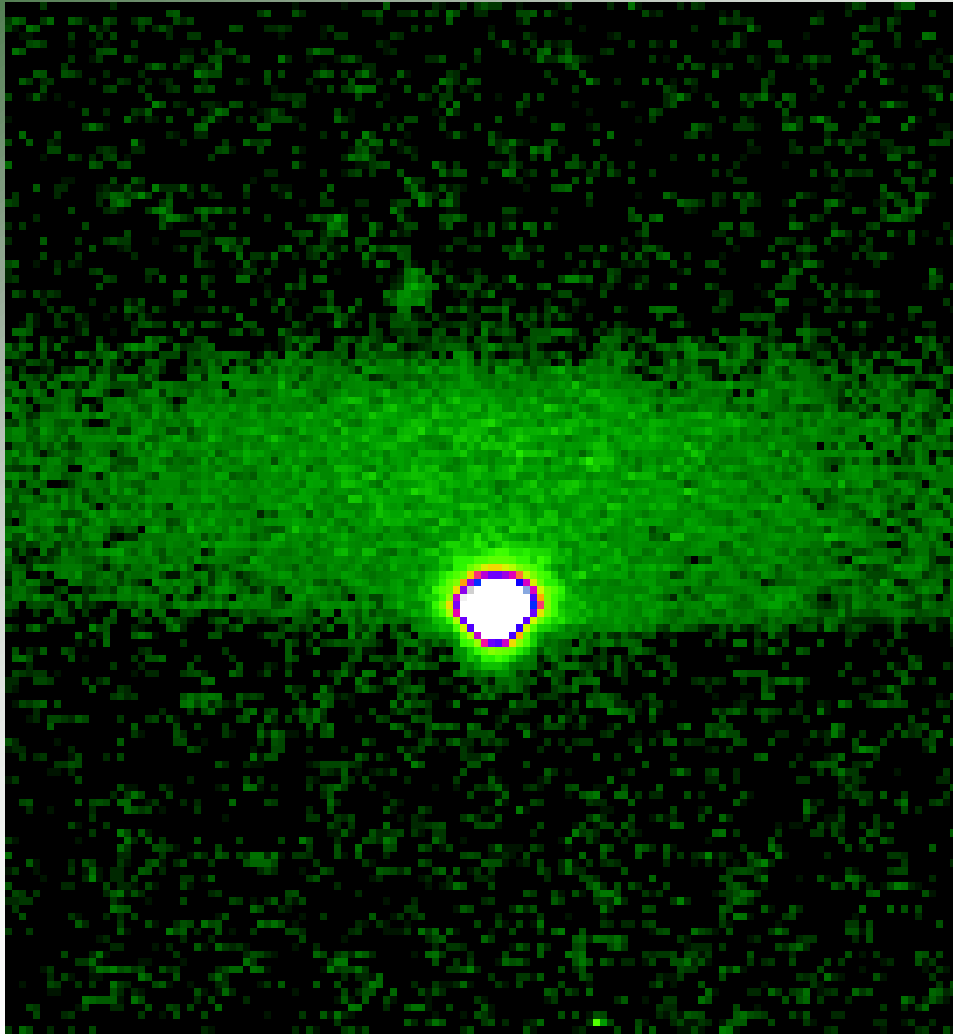


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IPlate Single Peak PSF



Specifications



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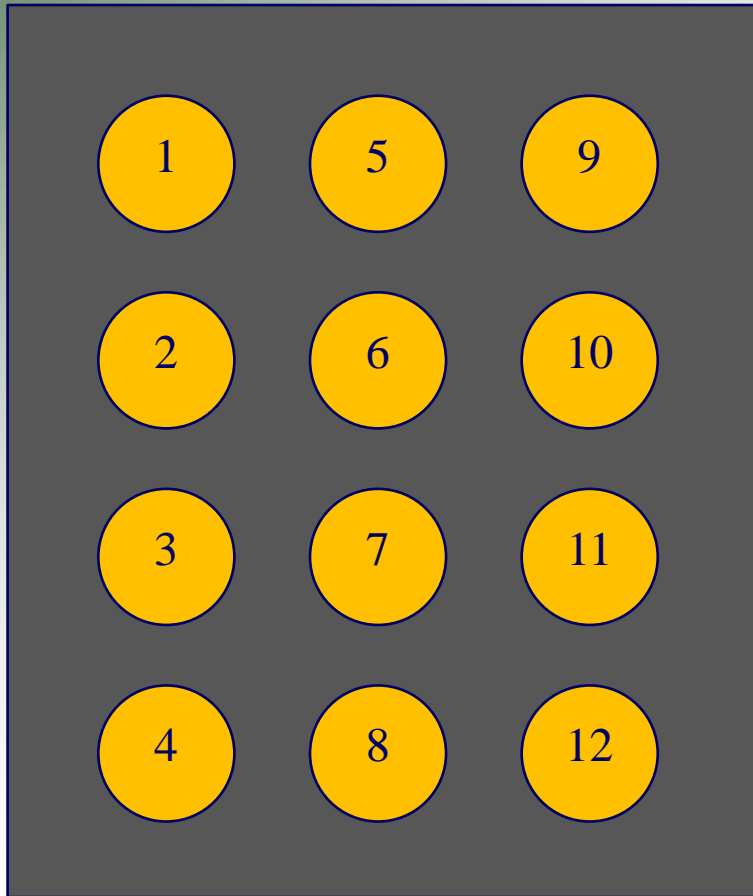
Dynamic Range

- $\text{dB} = 20 \log_{10} (\text{Ratio})$
- So the ratio = $10^{\text{dB}/20}$

- Quoted intra scene DR = 67.0dB = 2339
- Quoted inter scene DR = 75.4dB = 5888

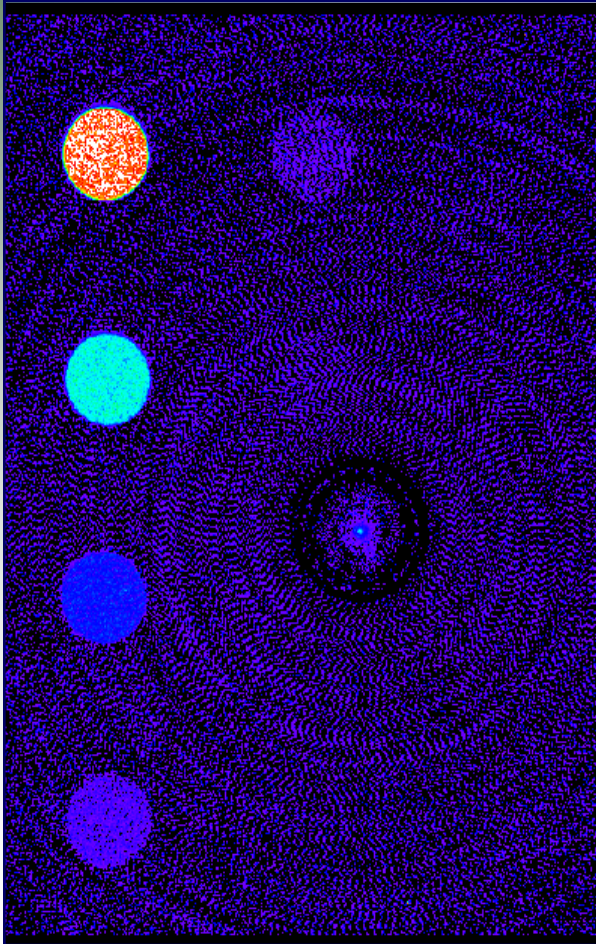
- Why the difference?

Intensity Test

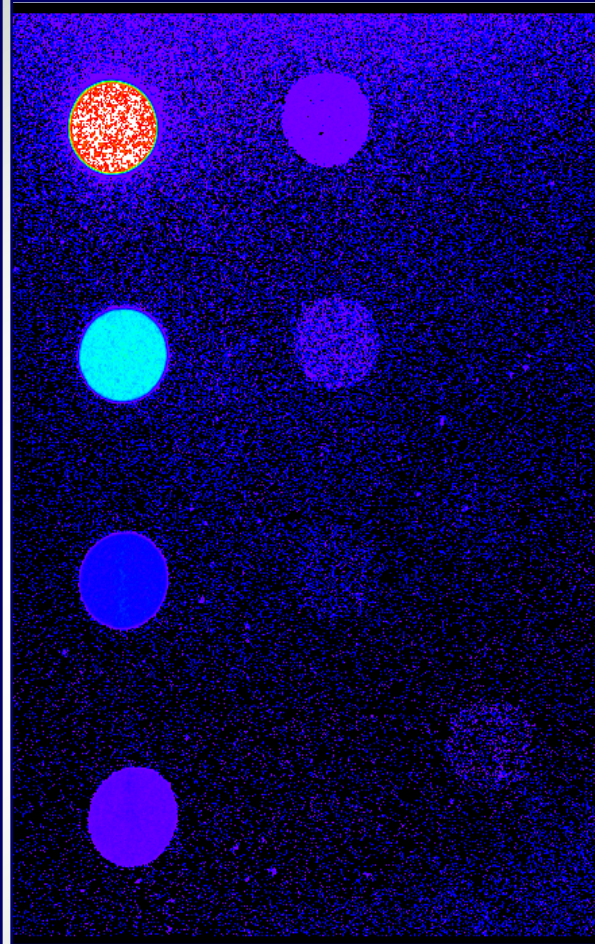


Graded Absorber Comparison

Mar Image Plate



ESRF-Thompson IIT / CCD



Daresbury MWPC

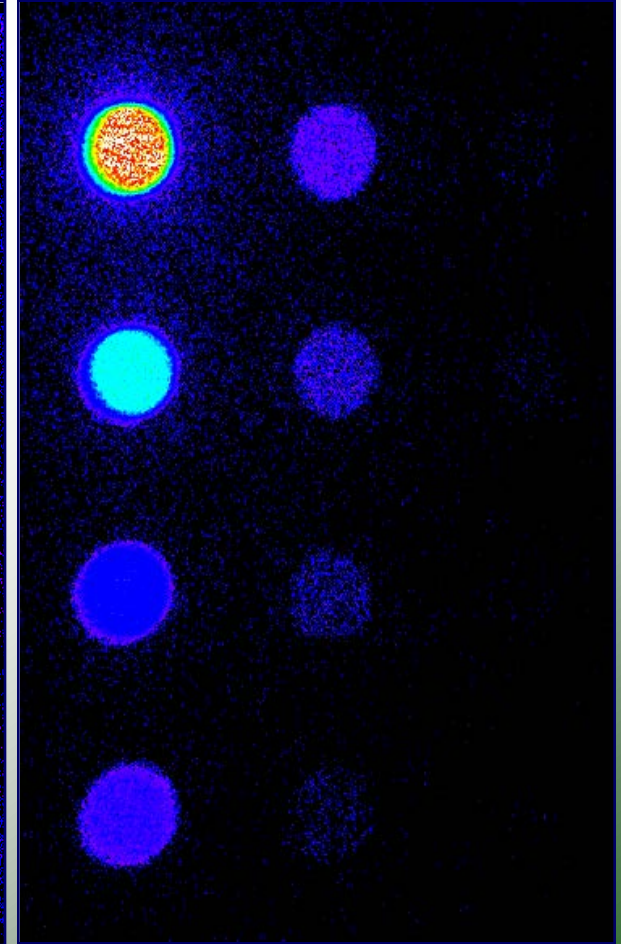
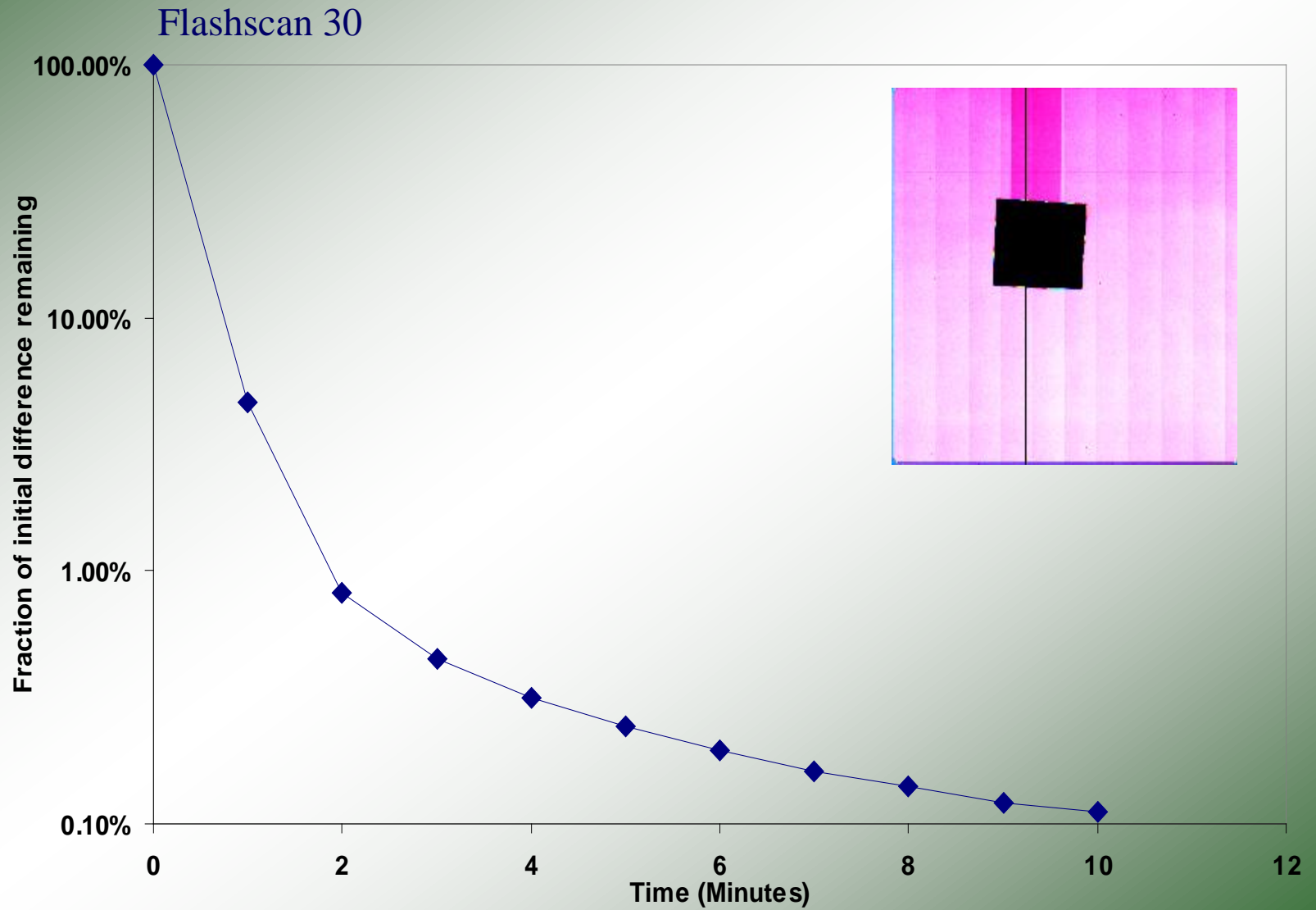


Image Lag



Specifications



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Well Depth

- Quoted well depth is $23000e^-$
- At $3eV / e^-$ hole pair a pixel will saturate with 8 x-ray photons of $10keV$
- Suddenly dynamic range is 8!
- Indirect detection is crucial to increase dynamic range
- Use a phosphor

Radiation Damage

- Indirect detection is important for another reason.....
- Medipix
 - ◆ Radiation damage at 40Gy = 1.3×10^{10} pht/mm² in the readout chip
 - ◆ Strong diffraction spots $\sim 10^6$ phts/mm²/s
 - Chip destroyed in ~ 8 hours
 - ◆ Direct beam (10^{10} – 10^{13} photons/mm²/s)
 - Chip destroyed in less than a second

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Sensitivity for Optical Photons

- 550nm photon $E = hc/\lambda = 3.6 \times 10^{-10}$ nJ
- So 1 nJ equates to 3×10^9 photons
- $1 \text{ cm}^2 = 3305785$ pixels
- So $1 \text{ nJ/cm}^2 = 908$ phts / pixel
- Quoted Sensitivity is 255 DN/nJ/cm²
- 1 Digital Number = 0.3 optical phts / pixel

- But what does this mean for x-rays ?

Sensitivity

- Ideal sensitivity is 1 DN per x-ray photon detected
- Many factors beside chip sensitivity
 - ◆ Conversion x-rays to light (1 photon/30eV typical)
 - ◆ Ability for light to escape phosphor
 - ◆ Transfer light from phosphor to chip, lens, FOT
 - Lenses poor $f1.4 = 10\%$ transmission (no reflections)
 - Fibre optic better but distortions

Specifications



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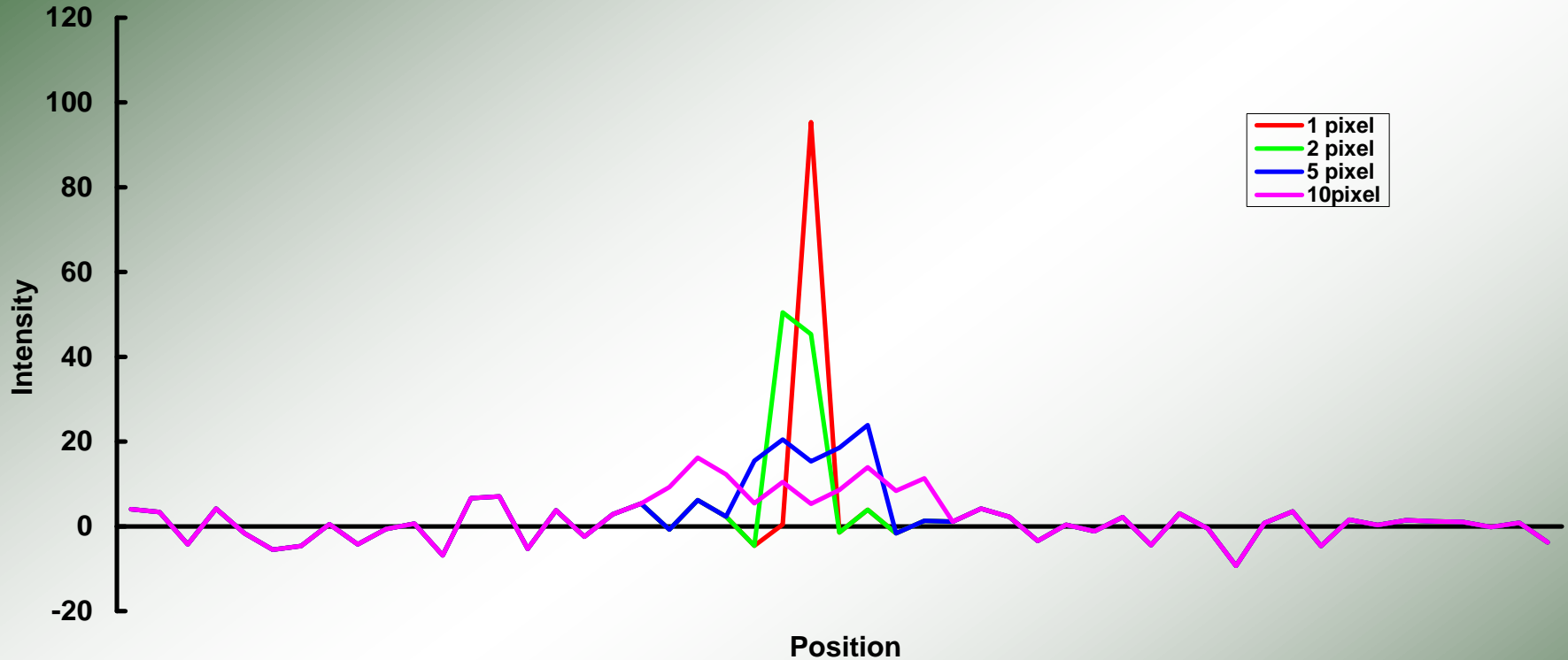
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Dynamic Range and SNR

- Datasheet DNR = 75.4dB or 5888
- Datasheet SNR = 43.0dB or 141 !!!!
- Why the difference?
- DNR = Max signal / Detector Noise
= $23000e^- / 3.2e^- = 7186 = 77.1\text{dB}$
- SNR = Max signal / All noise (inc. photon statistics)
= $23000 / \sqrt{23000} = 151.6 = 43.6\text{dB}$
 - ◆ Nb/ Poisson statistics apply to electrons as well as photons
- Difference between my calculation and their values is that they used a full well capacity of 20000

Real SNR

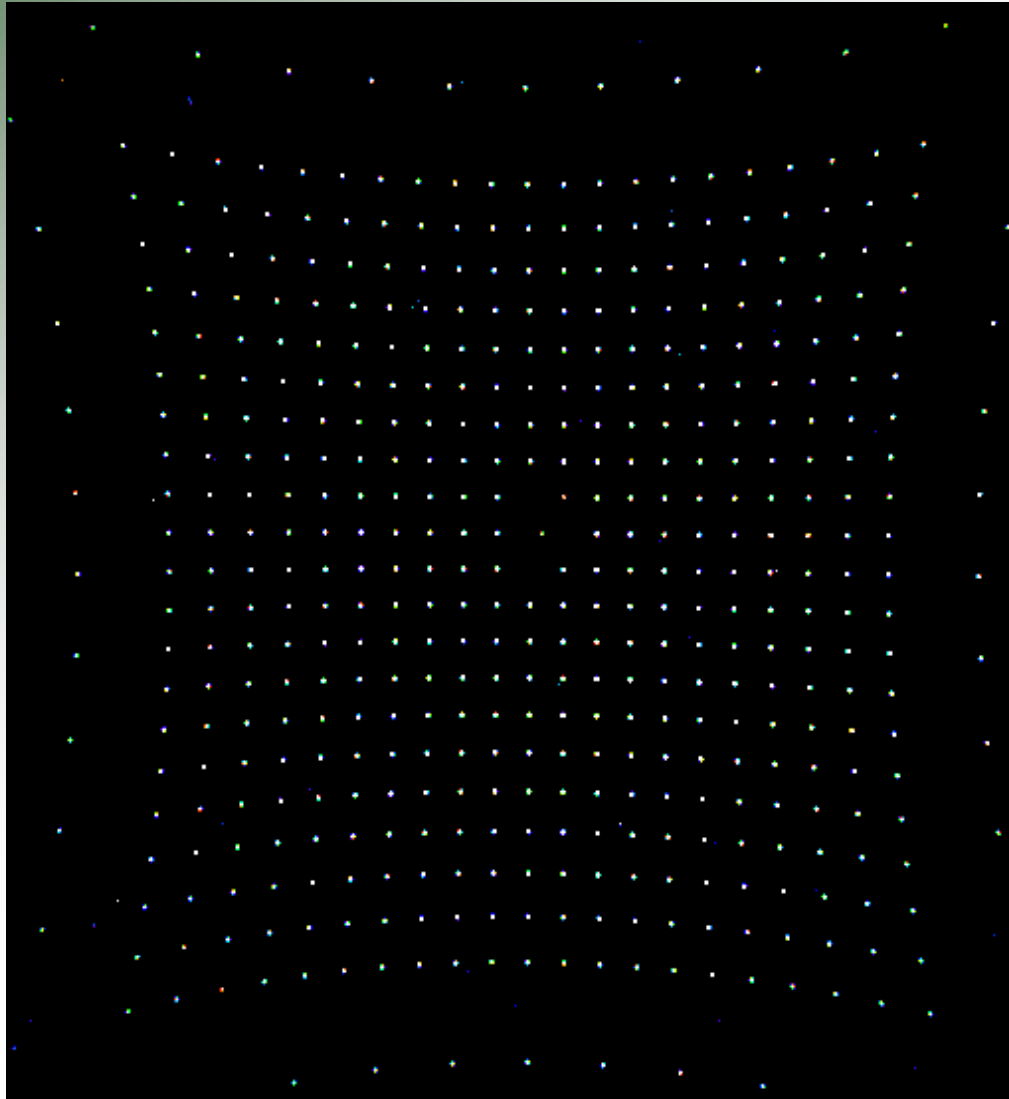


- Usually better to have signal in fewer pixels because each pixel has its own noise

Things not in Specifications

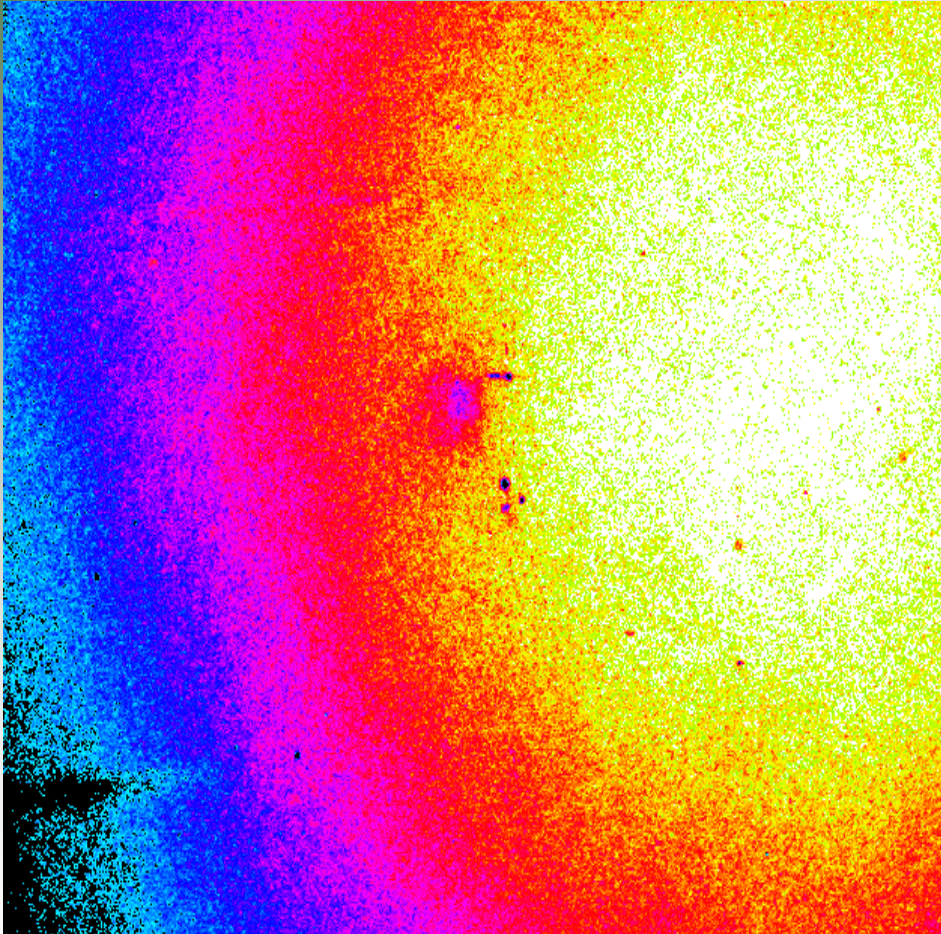
- Spatial distortions
- Sensitivity uniformity

Spatial distortion $x = f(y)$

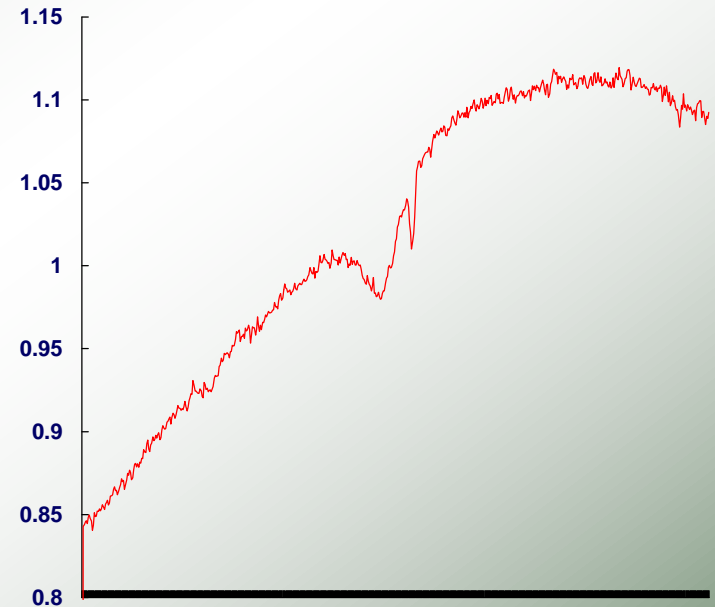


ESRF Image
intensifier
detector

Response to Uniform Illumination

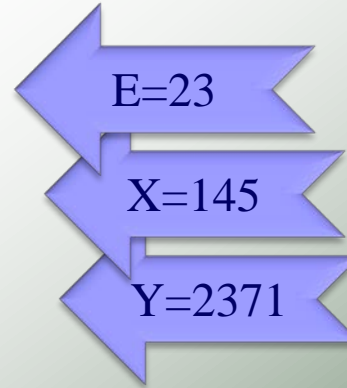
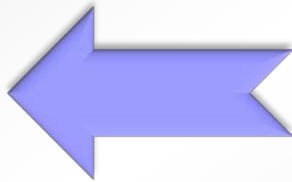
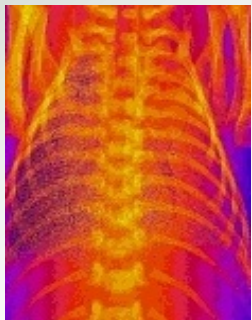
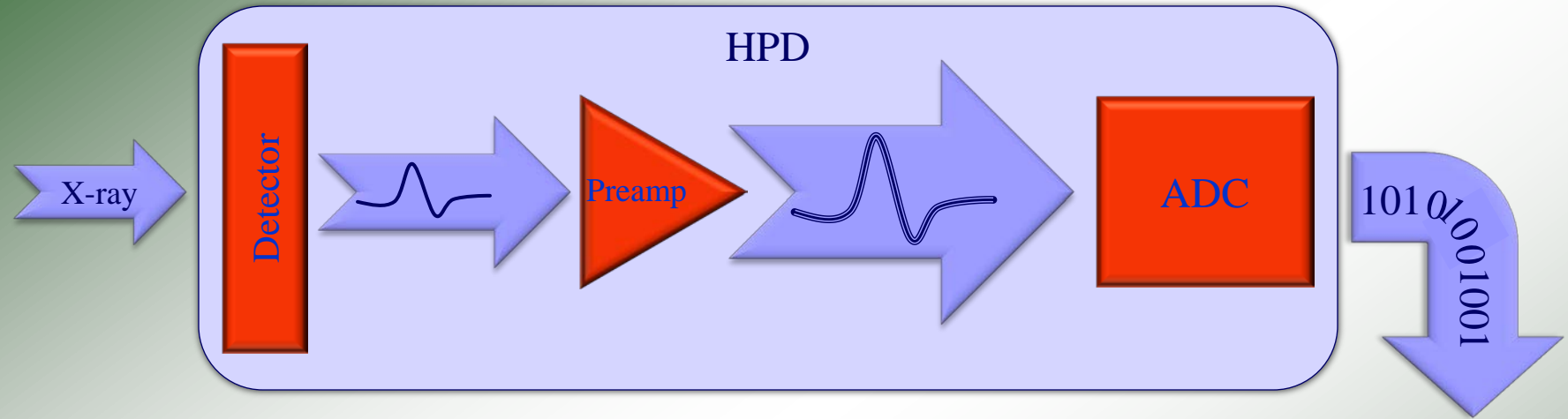


ESRF TV Detector
Thompson IIT & CCD



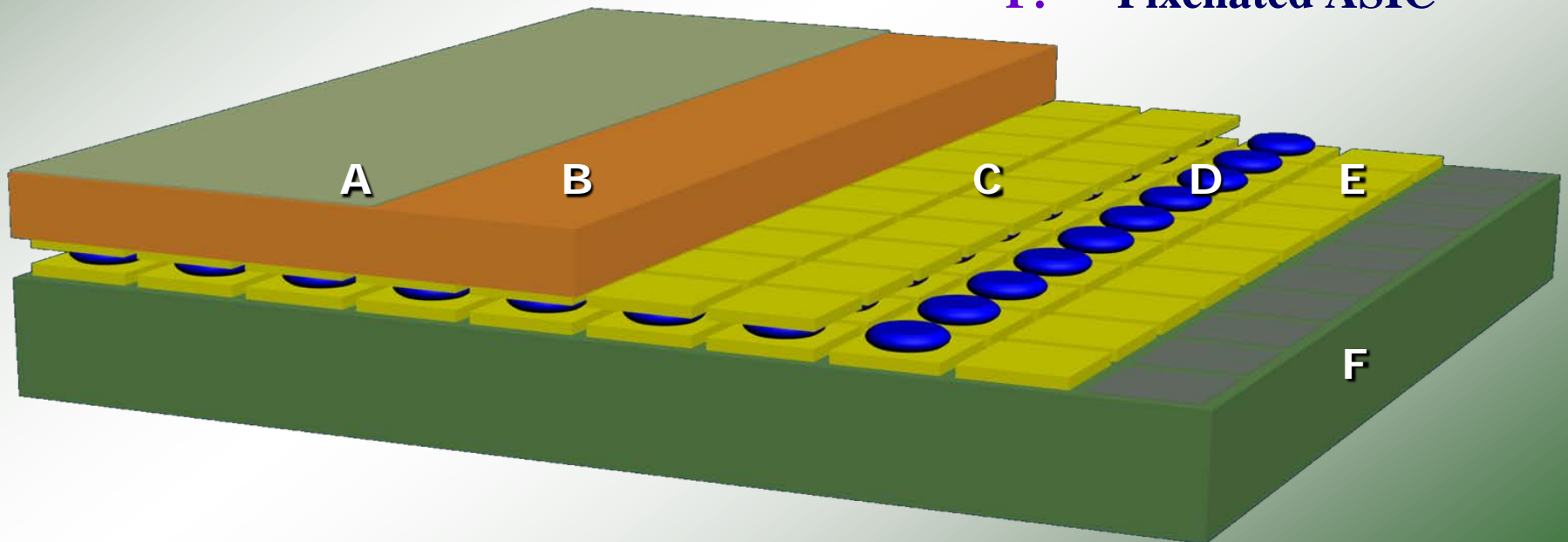
We would like sensitivity to be a constant, neither varying in time or position

Combine Imaging and Spectroscopy

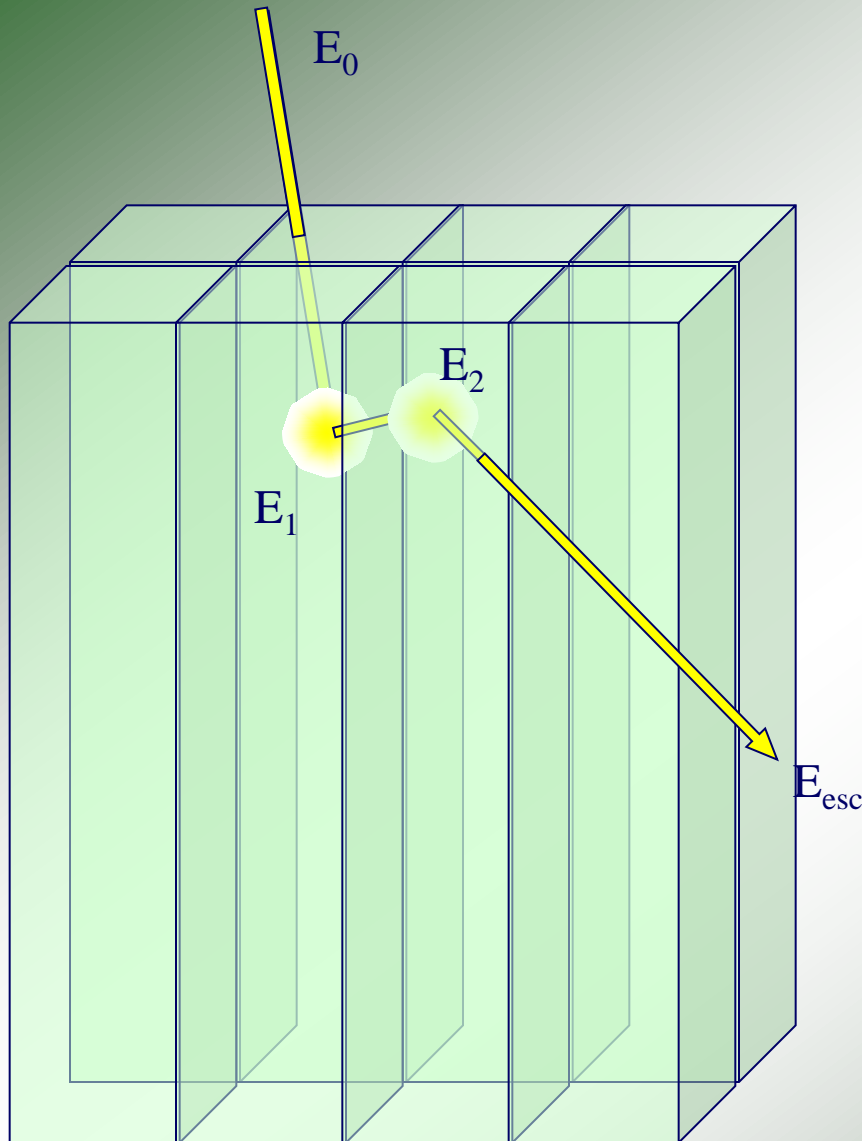


Pixel Array Detector

- A.** Top electrode
- B.** Pixellated semiconductor
- C.** Collection electrodes
- D.** Bump bonds
- E.** Input electrode
- F.** Pixellated ASIC

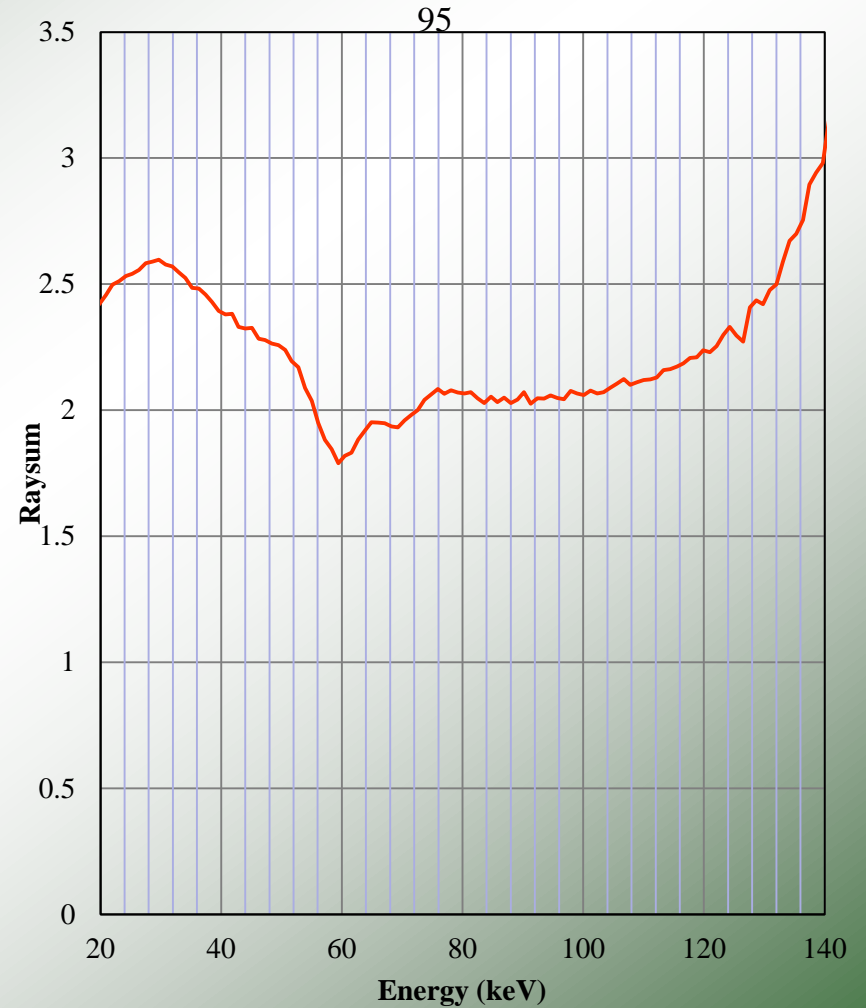
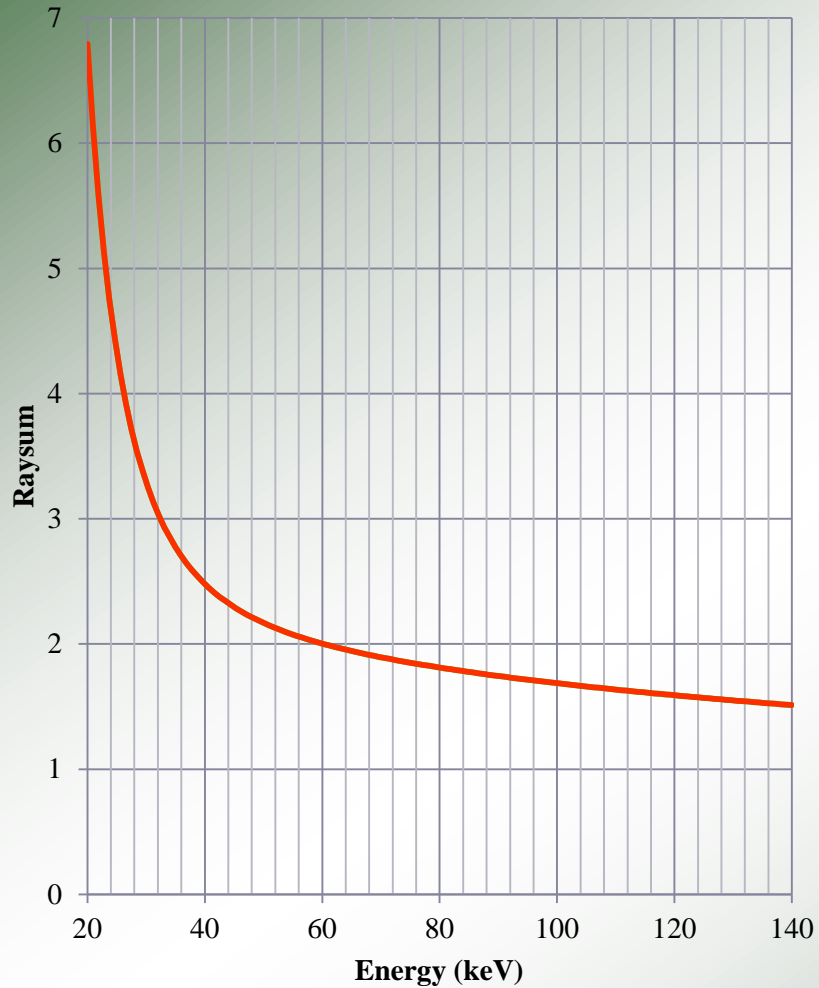


The Problem of Multiple Scatters



- We would like to know E_0 but.....
- $E_0 = E_1 + E_2 + E_{esc}$
- We don't know E_{esc}
- E_1 and E_2 are separate events
- So we must be able to associate multiple energy deposits as single input photon
- We must also minimise E_{esc}
- Not a simple problem!

Spectroscopic Imaging Reality



Detector Considerations

■ Intensity Measurement

- ◆ Uniformity across device
- ◆ Ageing, radiation damage
- ◆ Dynamic Range
- ◆ Linearity of Response
- ◆ Stability

■ Spatial Measurement

- ◆ Spatial Resolution
- ◆ Spatial Distortion
- ◆ Parallax

■ Energy Measurement

- ◆ Spectral Resolution
- ◆ Linearity of Response
- ◆ Uniformity of Response
- ◆ Stability

■ Time Measurement

- ◆ Frame Rate
- ◆ Photon Time Resolution

■ Others

- ◆ Size and weight
- ◆ Cost

Other Issues

- In addition to detector performance metrics such as
 - ◆ Spatial resolution, Spectral resolution, etc.
- Often we need to correlate with other parameters
- Requires that...
 - ◆ The detector respond to triggers
 - ◆ Be able to synchronise with other systems measuring multiple parameters

Counting Statistics

- Photons are quantised and hence subject to probabilities
- The Poisson distribution expresses the probability of a number of events, k occurring relative to an expected number, n

$$P(n, k) = \frac{n^k e^{-n}}{k!}$$

- The mean of $P(n, k)$ is n
- The variance of $P(n, k)$ is n
- The standard deviation or error (noise) is \sqrt{n}
- If signal = n , then $\text{SNR} = n/\sqrt{n} = \sqrt{n}$
- As n increases, SNR improves

Performance Measure - DQE

Perfect detector $SNR_{inc} = \sqrt{N_{inc}}$ $\therefore N_{inc} = SNR_{inc}^2$

Imperfect detector $SNR_{Non-ideal} < \sqrt{N_{inc}}$

We can define $N_{photons}$ that describes real SNR

$$NEQ = SNR_{Non-ideal}^2$$

Ratio of NEQ to N_{inc} is a measure of efficiency

$$DQE = \frac{NEQ}{N_{inc}} = \frac{SNR_{Non-ideal}^2}{SNR_{inc}^2}$$

Note that DQE is f(spatial and spectral frequencies)

DQE Comparison

DN-5 beam
2.6 μ Gy

